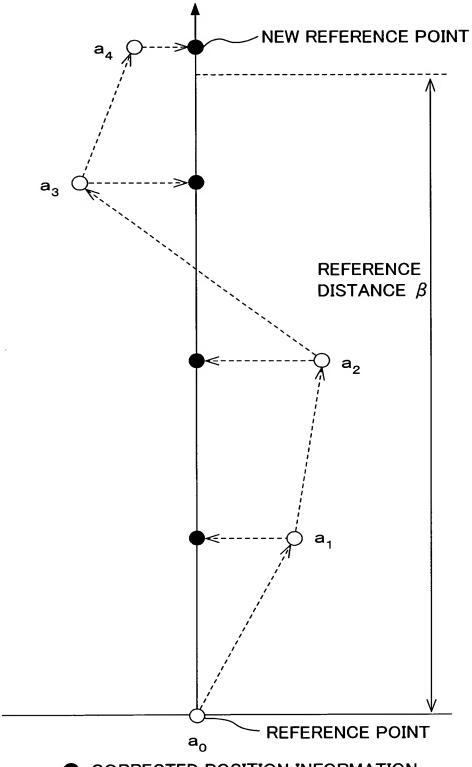


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FIG.2

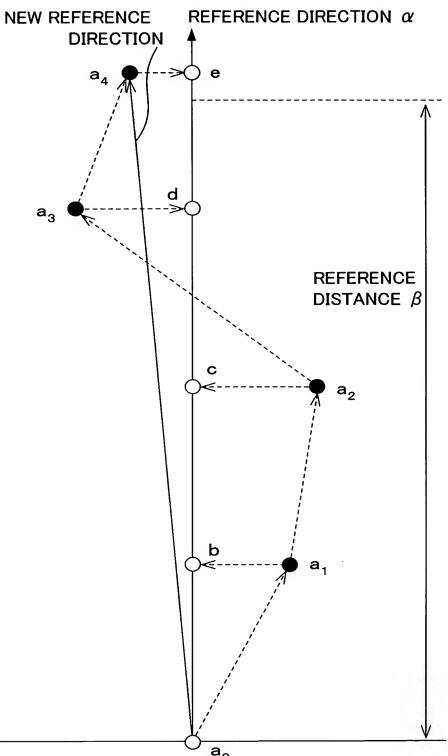
REFERENCE DIRECTION α



●: CORRECTED POSITION INFORMATION

FP3144S

FIG.3



ROUTE OF REFERENCE

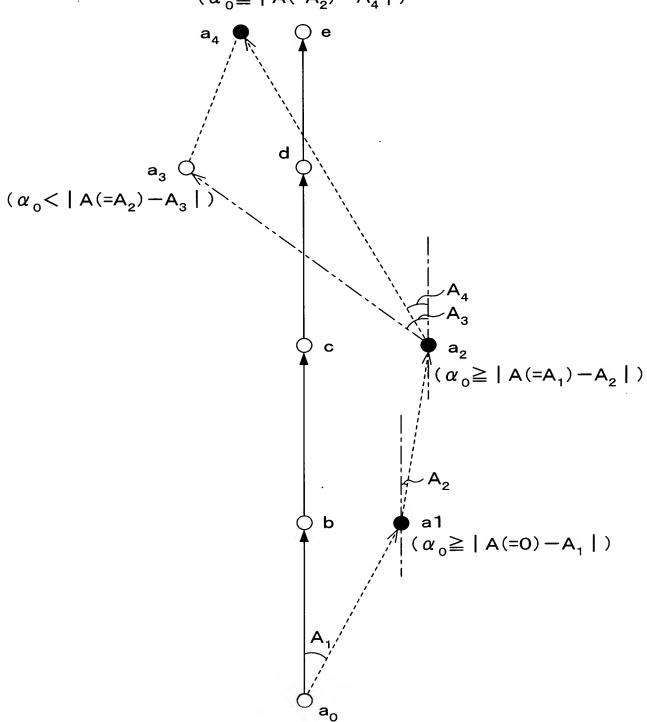
DIRECTION: $a_0 \rightarrow b \rightarrow c \rightarrow d \rightarrow e$

DISPLAYED ROUTE: $a_0 \rightarrow a_1 \rightarrow a_2 \rightarrow a_3 \rightarrow a_4$ OR $a_0 \rightarrow b \rightarrow c \rightarrow d \rightarrow e$

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FIG.4

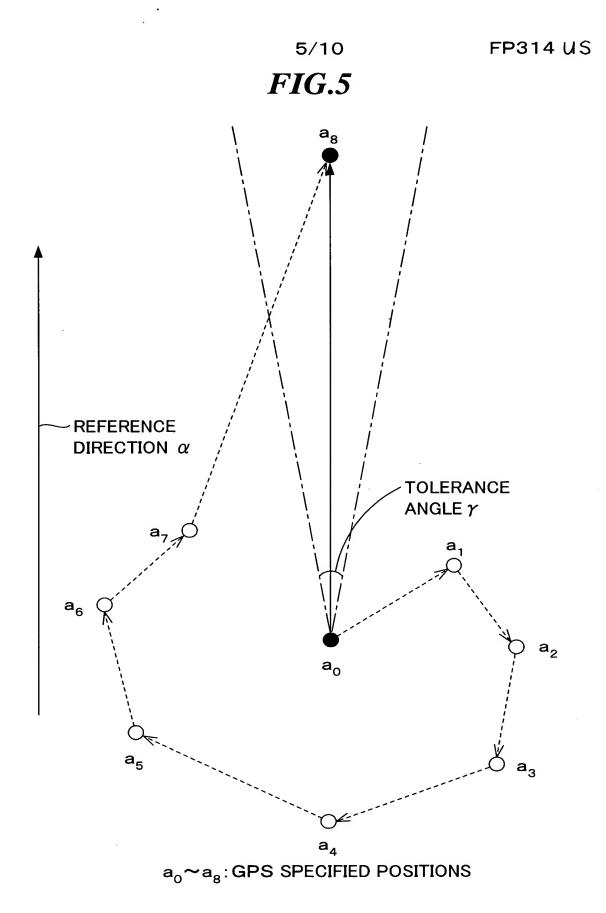
 $(\alpha_0 \ge |A(=A_2) - A_4|)$

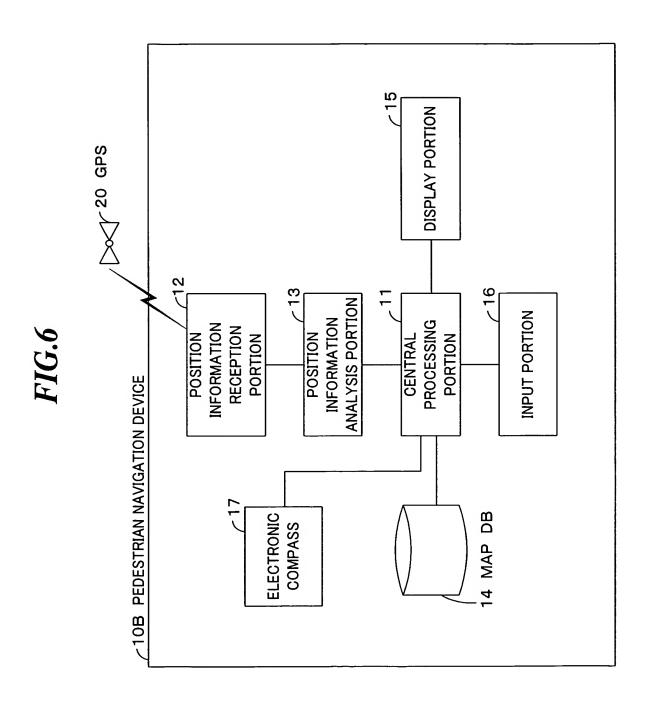


ACTUAL MOVEMENT ROUTE: $a_0 \rightarrow b \rightarrow c$

DISPLAYED ROUTE: $a_0 \rightarrow a_1 \rightarrow a_2 \rightarrow a_4$

TOLERENCE ANGLE: α_{o}

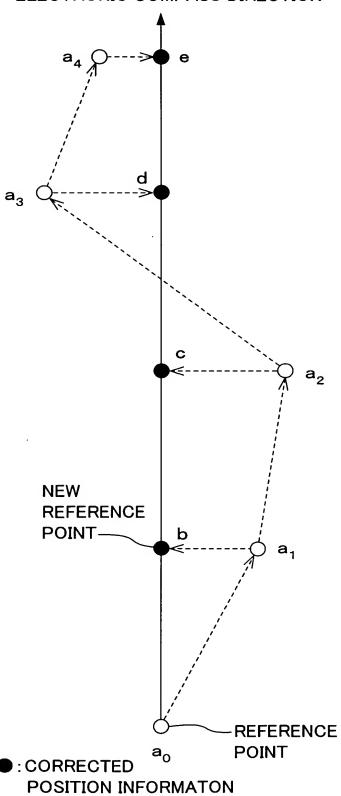


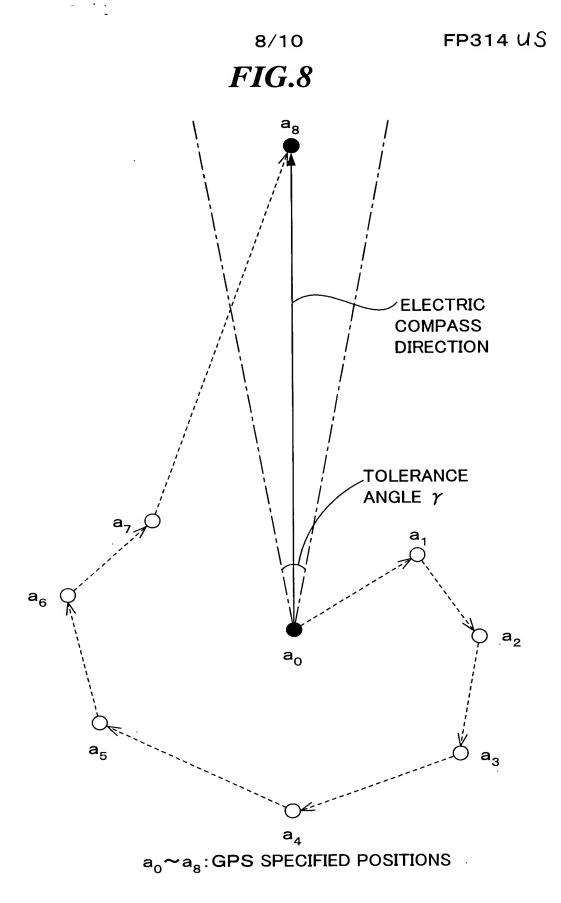


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FIG.7

ELECTRONIC COMPASS DIRECTION





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FIG.10

